



25256—82
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25256-82

**Rolling bearings. Tolerances.
Terms and definitions**

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1.24.	,
1.25.	<i>d</i> ,

1.26.

$$d_s(D_s) = \frac{^{\wedge}jfnax^{\wedge}b^{\wedge}smin}{2}$$

1.27.

$$d_m(D_m) = \frac{^{\wedge}smax^{\wedge}P^{\wedge}s'min}{2}$$

$$/ - \frac{^{\wedge}jfnax^{\wedge}b^{\wedge}smin}{g} /$$

1.28.

$$dmp(\& \quad) =$$

1.29

$$B_s(C_s) =$$

1.30.

$$(\quad)$$

$$R = \frac{^{\wedge}jfnax^{\wedge}b^{\wedge}smin}{2}$$

$$- \frac{^{\wedge}smax^{\wedge}P^{\wedge}s'min}{2}$$

1.31.

$$T_s(H_s) =$$

1.32.

$$D_{ws}$$

1.33.	-
1.34.	-
Dwmp	
1.35.	-
Lws	,
1.36,	-
Lwm	
	$\overset{\wedge}{L-wm-2} \overset{\wedge}{usmaxH} \overset{\wedge}{ters \cdot min}$
2.	
2.1.	
2.1.1.	
$\overset{\wedge}{d_s}$	$\overset{\wedge}{d_s} = ds \sim d$
2.1.2.	-
$\dot{d}m$	$\overset{\wedge}{d_m} \overset{\wedge}{dm} \hat{d}$
2 . .	-
2.1.4.	,
	$\sim d_m p \ d$

2.2.

2.2.1.

 D_s $Q_s—D_s—D$

2.2.2.

 $=D_m—D$

2.2.3.

 $A_D = D_{mp} — D$

2.3.

()

2.3.1.

 $s(\mathfrak{s})$ $s — (— C_s —)$

2.3.2.

 $(s(\mathfrak{s}) \&)$ $s — T_s — (— h = H_s - H)$

2.4.

2.4.1.

 ws $)_{ws}$

2.4.2.

 $)_{wm} — Dwm$

2.4.3.	-	-
	*	
2.4.4.	,	-
	()	-
	$v^o - l >$	
2.4.5.	-	
	WS	$= L_{WS} - L_w$
2.4.6.	,	

3.

3.1.	-	-
		$\wedge d_m p \sim mp_{max} - pin in \bullet$
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	,	
3.2.	-	-
3.3.	-	-
		$\wedge / Dmp_{min.}$

3.4.

3.5.

3,6.

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3,7.

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(_s " — 1)

3.8.

^vD_{wmp}

Bwmpmax Dwmpmiw

3.9.

3.11.

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3.12.

4.

4.1.

Kt

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4.4,
 $S^*(S_e)$
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4.5.

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4.6.

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(- - - - -) , (- - - - -)

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5.

5.1.

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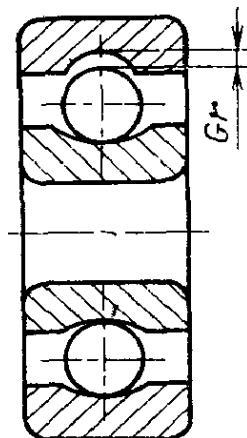
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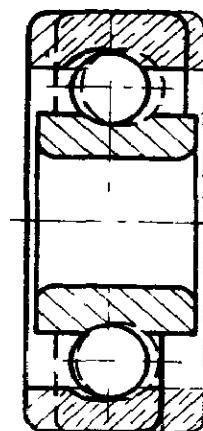
6.

6.1.

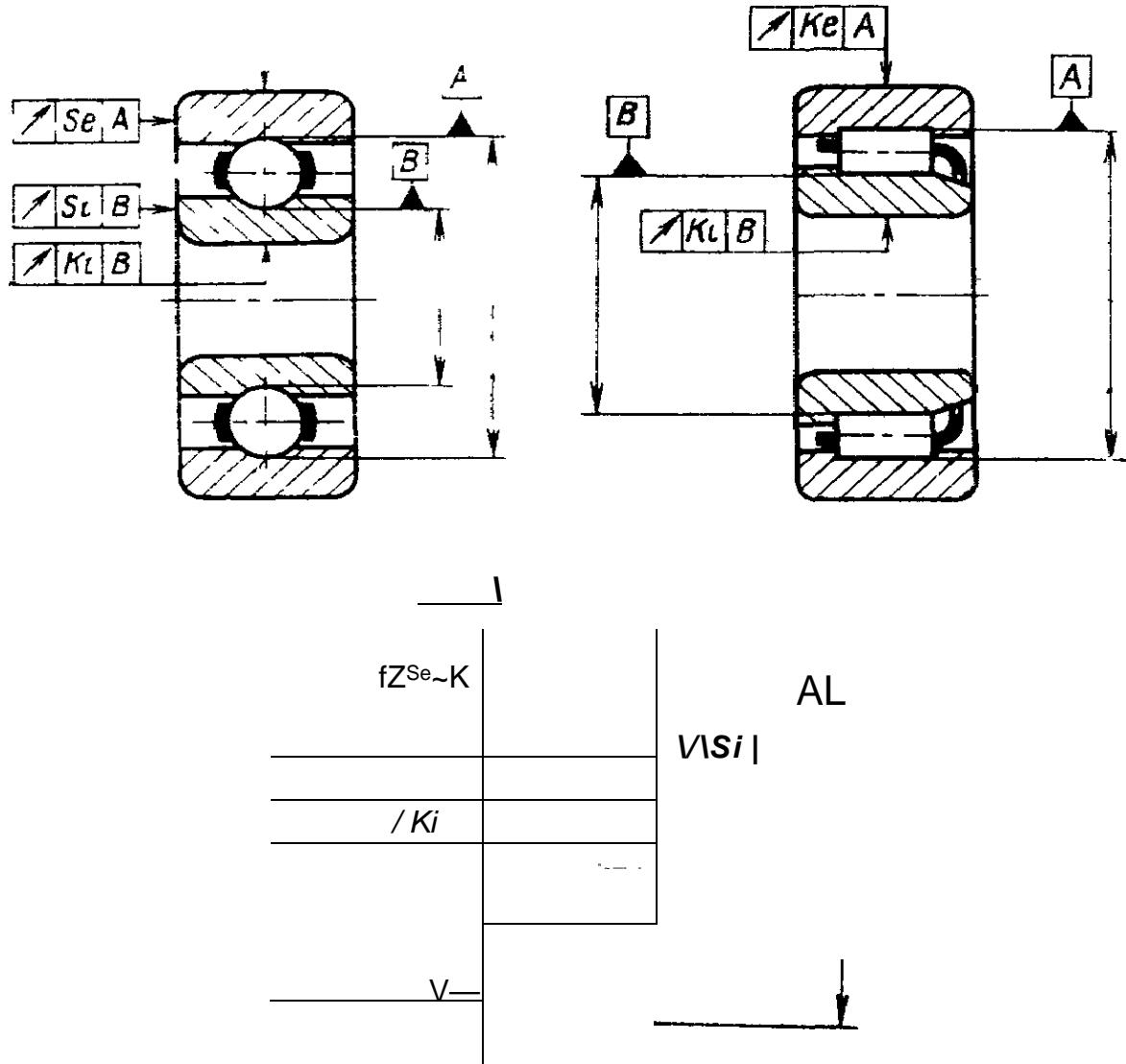
8.2.

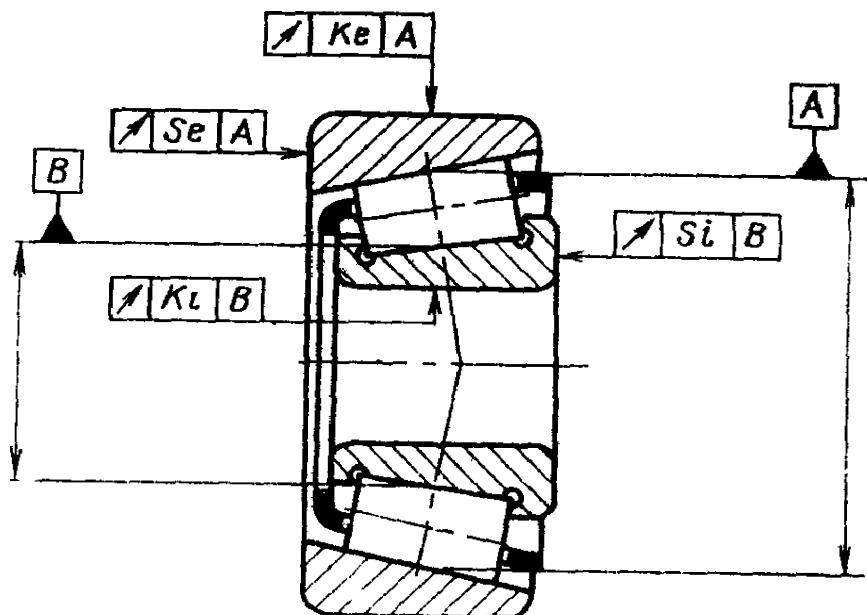
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				6.2
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				3.1

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				1.29
				1.30

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