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INTERSTATE COUNCIL FOR STANDARDIZATION, METROLOGY AND CERTIFICATION
(ISC)

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Industrial cleanliness. Hydrodynamic method of cleaning from contaminations in gas and fluid systems of machines and mechanisms

— 2008—03—01

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		(), [/ () ²]	-1 ,	(), [/ () ²]	-1 ,
4 ; 5 ; 6	15 20 .				
8; 10	25 35 .				
12; 16	40 60 .	0,5 „ * .	40 20 .	0,7 „ / .	70 50 .
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32; 40	110 140 .				

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6; 8; 10	30 40 .	0,7 „ * ^{01/}	350 100 .	0,7 „ /	250 60 .
12; 16	50 70 .	0,8 „ *			
20; 25	80 100 .				
* — ().					

5**5.1**

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5.2**5.2.1**

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5.2.2

(.5) (.8) ().

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5.3**5.3.1**

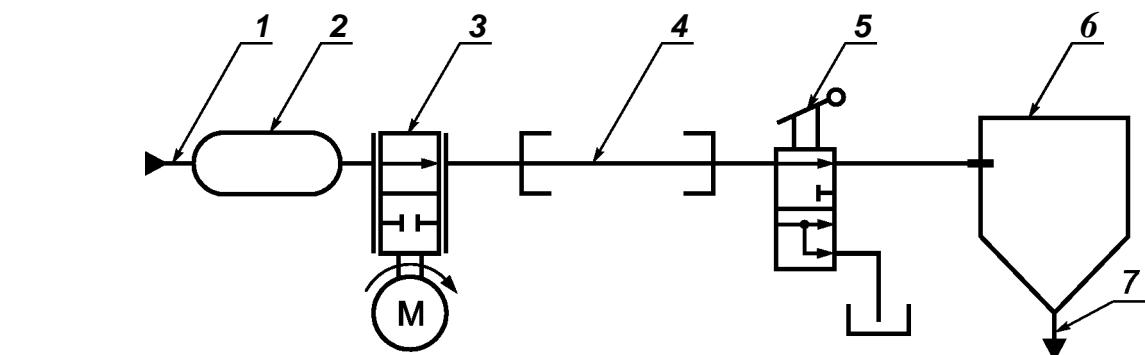
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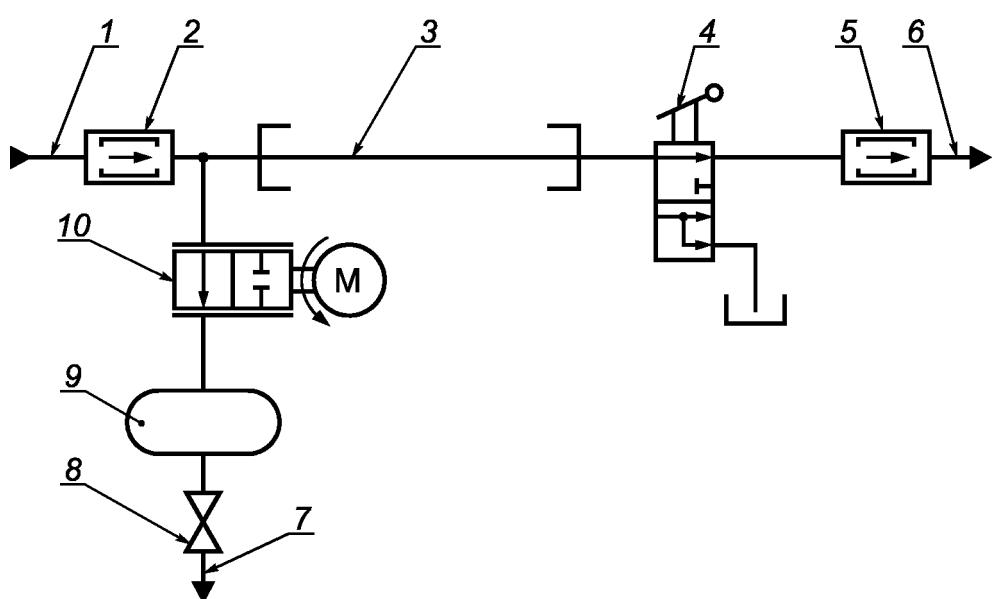
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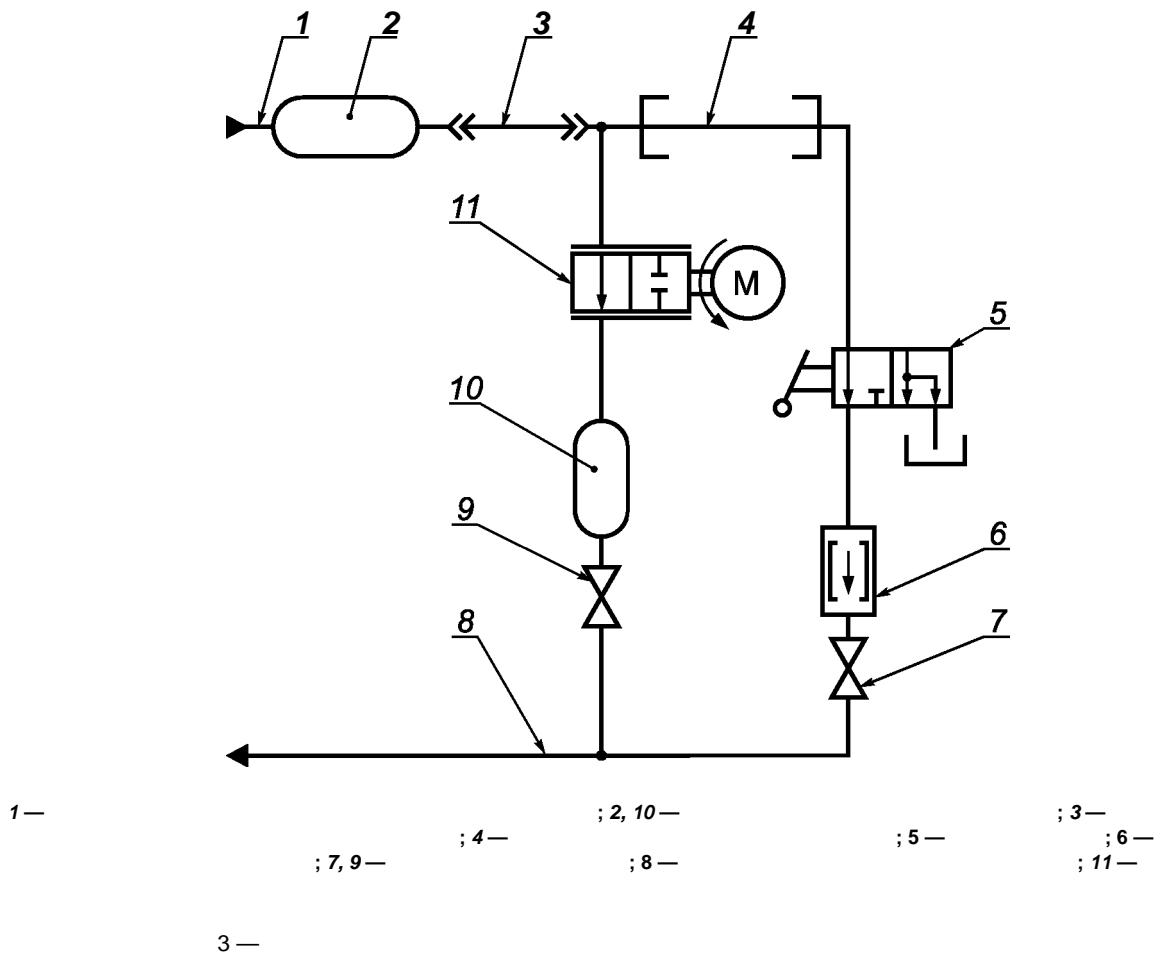
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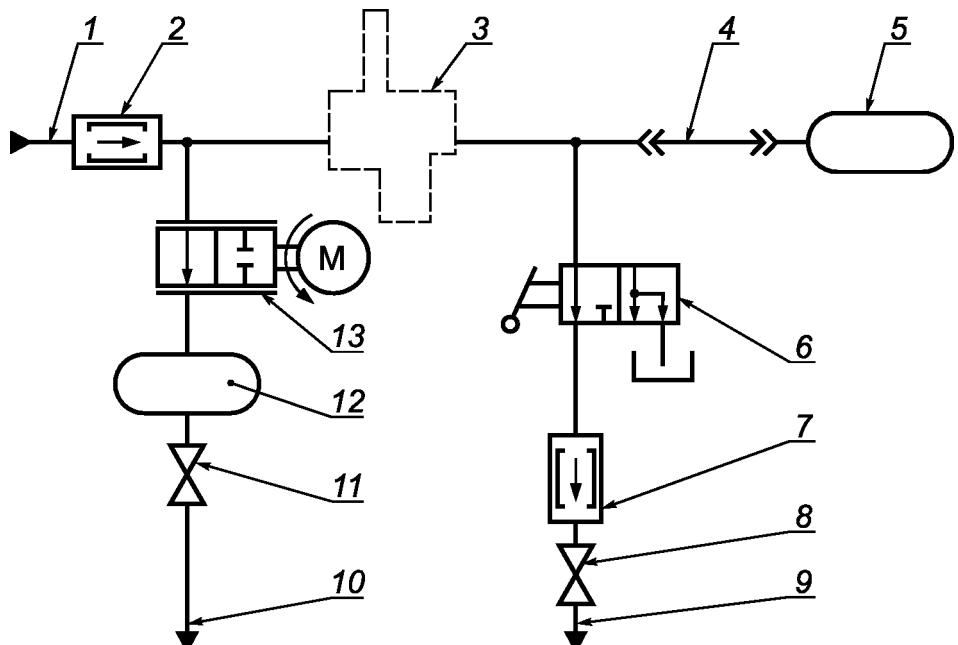


1 — ; 4 — ; 5 — ; 2 — ; 6 — ; 7 — ; 3 —
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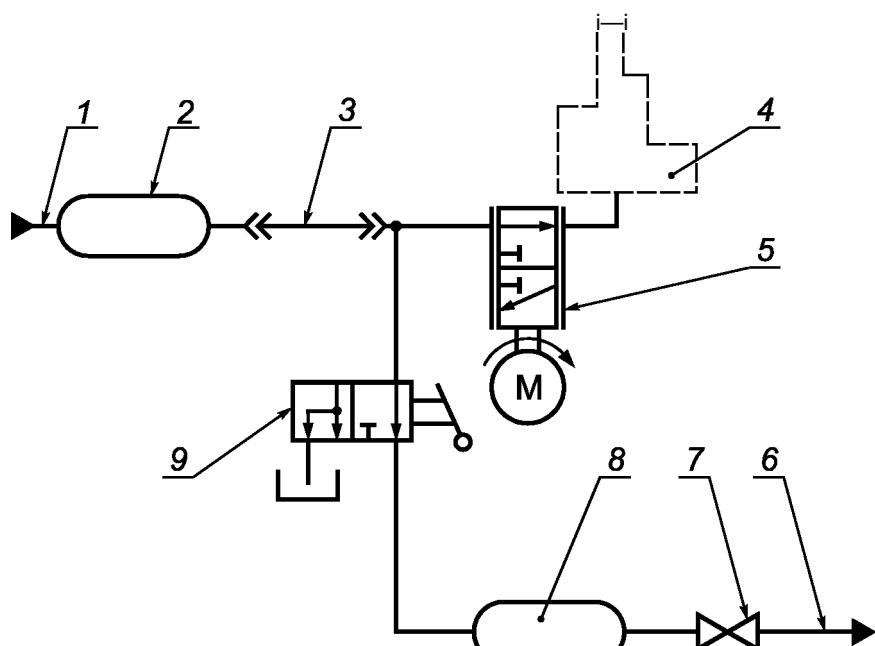
1 — ; 4 — ; 6,7 — ; 2,5 — ; 10 — ; 8 — ; 3 — ;
2 — ; 9 —





1— ; 4— ; 8, 11— ; 9, 10— ; 2, 7— ; 5, 12— ; 13— ; 3— ; 6—

4—



1— ; 4— ; 7— ; 2, 8— ; 5— ; 9— ; 3— ; 6—

5—

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.1

.1.1

$$Q_0 = Q_0 + A_q \sin \text{cof},$$

(.1)

$$\frac{Q_0}{A_q} = \frac{(\quad)}{(\quad)}, \quad , \quad , \quad ;$$

$$\frac{t}{t} = \frac{(\quad)}{(\quad)}, \quad , \quad , \quad ;$$

[1].

$$.1.3 \quad (\quad)$$

$$Q = \frac{A_p_{\text{bx}}}{Z_{\text{bx}}}, \quad (.2)$$

$$\frac{-}{Z_{\text{bx}}} = \frac{(\quad , \quad /(\bullet^2))}{(\quad)}, \quad , \quad /(\bullet^4). \quad -$$

$$.1.4 \quad Z_{\text{bx}}, \quad /(\bullet^4), \quad (\quad , \quad).$$

$$d^{1/2} / d^X \quad +4< \quad (.3)$$

$$\frac{X}{Z_{\text{nc}}} = \frac{(\quad)}{(\quad , \quad /(\bullet^3))};$$

$$Z_{\text{nc}} = \frac{(\quad , \quad /(\bullet^4))}{(\quad)};$$

$y = V = i;$
 $X =$

$$Z_n, \quad /(\bullet^4),$$

(.4)

$$2 \quad - \frac{1}{1!}$$

$$= 2,718.$$

$$\frac{-}{-} = \frac{(\quad , \quad /(\bullet^2))}{(\quad)};$$

$$, \quad , \quad , \quad ;$$

$$, \quad , \quad , \quad ;$$

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.2.1

, , :

$$\frac{Q_0}{Q_0} = \frac{25\%}{Q_0} \quad 50\%;$$

$$/ , ,$$

$$l_{\max} = \frac{\pi^2}{16\lambda} \cdot \frac{d_y^5}{\rho_{\text{x}}} (0,7 - 0,8) \cdot P_p \cdot \frac{1}{Q_0^2}, \quad (.5)$$

$$- \quad \quad \quad (\quad \quad \quad) \quad \quad \quad , \quad /(\bullet^2); \\ - \quad \quad \quad (\quad \quad \quad).$$

.2.2 17216.

$$.3.1 \quad \quad \quad (\quad \quad \quad) \quad \quad \quad , \quad / (\quad \bullet \quad ^2),$$

$$A_p = \frac{Z_{\text{arp}} Z_{\text{n.c.}}}{Z_{\text{arp}} + Z_{\text{n.c.}}} A_Q, \quad (.6)$$

$$Z_{\text{arp}} = \dots, \quad /(\quad^4 \bullet \quad).$$

$$V_{arp} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}, \quad I = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad J = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}, \quad K = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\Delta P = E_{\infty} \frac{\Delta V_{\infty}}{V_{\text{arp}}} , \quad (.8)$$

$$\frac{1}{1-x} = \frac{1}{1-\left(\frac{x}{1+x}\right)^2} = \frac{1}{1-\frac{x^2}{(1+x)^2}} = \frac{(1+x)^2}{1+x^2} = \frac{1+2x+x^2}{1+x^2},$$

$$A_p = \frac{\rho_{\infty} a^2}{\omega V_{app}} A_Q. \quad (.9)$$

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.2.1

$$(\quad\quad\quad), \quad , \quad /(\bullet^2), \quad \quad \quad :$$

(.1)

$$\wedge \quad -(\wedge \quad) \wedge \quad \vee \quad , \quad (.2)$$

$$\begin{aligned}
 & () ; () - & , \\
 & ; - & () \\
 & / ; / - & ; , / (\bullet^2) ; \\
 & ; - & , / (\bullet^2) . \\
 & / ; / & .1 .
 \end{aligned}$$

. 1

3,2 5,0 . 5,0 » 7,5 » » 7,5 » 10,5 » » 10,5 » 12,5 » » 12,5 » 14,5 »	,	,	,	/
		0		0
		0,05		0,03
		0,10		0,05
		0,20		0,10
		0,25		0,10

17

.2.

.2

	W_G
10⁴	0,65
10⁵	0,65
10⁶	0,45
10⁷	0,35

(), ()

(KJ)

(.)

$$\bar{g}^{\wedge} \quad (.4)$$

$$\begin{aligned} ; & - \\ ; 8 & - \\ - & \\ ; & ; ; s_T; - \\ - & \\ ; & , /(\bullet^2), \\ - & \end{aligned}$$

$$2 \quad (.5)$$

$$, + " \quad (.6)$$

$$\rightarrow \frac{\wedge}{2}, \quad (.7)$$

$$" - \frac{\wedge}{2}, \quad (.8)$$

$$\begin{aligned} ; a_{\min}; & ; T_{\min} - \\ & /(\bullet^2). \\ (&) \end{aligned}$$

$$\frac{\wedge - \wedge_{\min}}{2}. \quad (.9)$$

$$\underline{\wedge} \sim \wedge_{\min}. \quad (.10)$$

$$= ; \quad (.11)$$

$$= . \quad (.12)$$

.2.2

$$(\quad \quad) ,$$

$$; - \quad , /(\bullet^2).$$

3000

$$^\circ \quad ^{^\circ 1 \wedge} \quad ^{^\wedge 1 >}$$

$$\begin{aligned} \wedge; & -_1 - \\ 3000 & , \quad , /(\bullet^2). \end{aligned}$$

$$= > = >$$

$$; - \quad (\quad \quad) , /(\bullet^2).$$

.2.3

$$\begin{aligned} ; & ; \\ ; & ; \\ (&) \end{aligned}$$

$$2 \quad (.13)$$

(.14)

24

(.13, .14).

$$m-, \quad /(\bullet^2);$$

$$\wedge \max_{2/7} u \quad (. 15)$$

$$\hat{\alpha}_{\min} = \frac{\min d_w}{2\gamma} \quad (1.16)$$

$$; P_{min} - \frac{h}{d_y} - \left(\frac{h}{d_y} \right)^2, \quad , \quad /(\bullet^2);$$

.2.1;

$$= \quad = -_1 -$$

23 24

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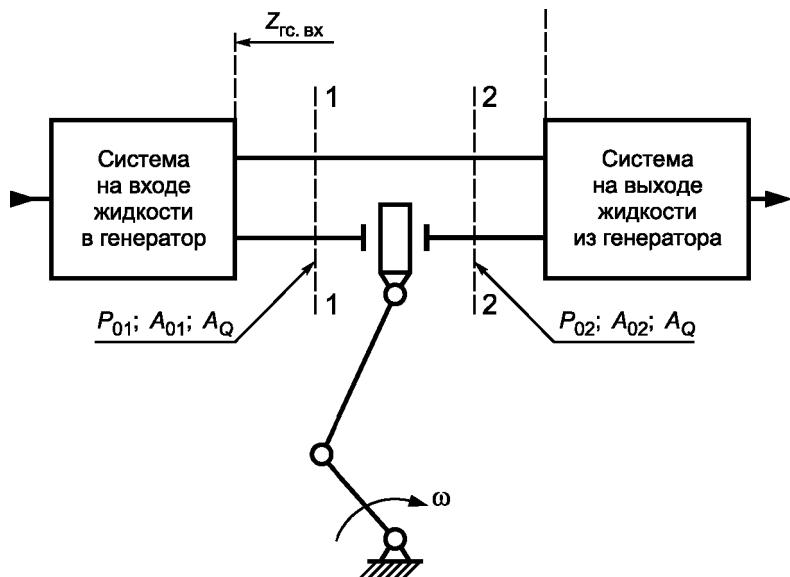
$$< ; \quad - \quad \underline{\quad} \quad (\quad \quad ; \quad \quad) \quad , \quad /(\quad \bullet \quad ^2);$$

.2.3 .2.4.

(. .)

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.1 —

.2

$$Q, \frac{3}{}, .1,$$

$$Q = pF(f) - [P_{01}^* - P_{02} + \sin(\omega f + \phi_p) - A_p \sin(\omega f + \phi_p)], \quad (\text{B.1})$$

$$\begin{aligned} F(f) &= ; \\ ;_2 &= ; \\ (P_i; q)_2 &= ; \\ ;_{01}; ;_{02} &= ; \\ ; &= ; \\ ; &= ; \\ ; &= ; \end{aligned}$$

$$“ \wedge .1 \wedge 0 ”$$

$$m = \overline{\cup} \overrightarrow{z}$$

$$z \sim \wedge .2 \wedge 0 ”$$

$$(2 - 31^*9 \wedge .2 ”$$

(-2)

(.)

(-4)

(-5)

 $Z_{rc1}; Z_{rc2} —$

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$$(.4)), /(\wedge 4 \bullet);$$

$$01 = 2^> A_{Pj} + \dots$$

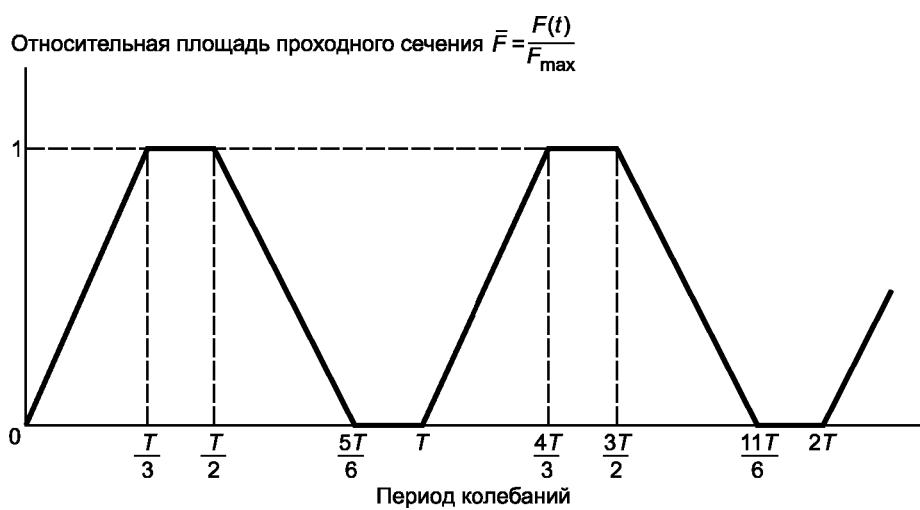
$$F_{\max}, \dots^2,$$

Q

2. . .

$$, /(\bullet^2).$$

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.2 —

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— 15 .

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$$F_{\max},$$

$$\frac{d^2}{dt^2} \left(\frac{dZ_{Tp}}{dt} \right) = \frac{16}{n^2 dy} + \frac{1}{8 \cdot dV J} > 4_0, \quad 3/ \quad (.2);$$

(.1)

$$\frac{dL_{Tp}}{dy} = \frac{d}{dt} \left(\frac{dZ_{Tp}}{dt} \right) = \frac{1}{dV J} \frac{d}{dt} \left(\frac{16}{n^2 dy} \right) = \frac{1}{dV J} \frac{1}{8 \cdot dV J} \frac{d}{dt} \left(\frac{16}{n^2 dy} \right) = A_q Z_{Tp}.$$

(-2)

.1.2

1.

, /(\bullet^2),

(.)

$$\frac{\partial^2}{\partial y^2} \frac{-16}{J^2} / 2A_q^2 +$$

, /(\bullet^2).

(-4)

$$Q_{Ham} = \frac{1}{2} \frac{\partial^2}{\partial y^2} + A_q^2.$$

.2

.2.1

(.2) — (.4).

.2.2

$V, \quad 3(\dots \quad 1-3)$

$$V = \frac{1}{2} A_q^2,$$

(-5)

$$\frac{1}{2} \frac{\partial^2}{\partial y^2} + V = \frac{1}{2} \frac{\partial^2}{\partial y^2} + \frac{1}{2} A_q^2 + V =$$

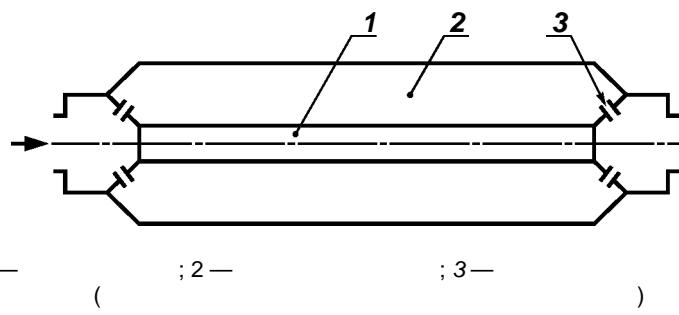
$$\dots - 4 \dots + V = \frac{1}{2} A_q^2 + V =$$

(.6)

$$\frac{d^2}{dy^2} \left(\frac{d^2}{dy^2} \right) = \frac{1}{2} A_q^2 + V =$$

.2.3

.1.



.3.1

.2.2, .2.3 (/ , ,).

$$d \quad \cdot \cdot \cdot k.7.\geq \} \quad \quad \quad (-7)$$

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V. 3

(. 8)

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V =

$$, \quad /(\bullet^2);$$

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0,0005	0,01 0,012 .
0,0005 0,001 .	0,016 0,018 .
0,001 0,003 .	0,02 0,22 .

.3.3

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$$/ = \frac{id \wedge a^2}{4^{(\mathbb{R})}} \quad (\text{.10})$$

d_y —

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$$AV = V_n, \quad (.11)$$

— , /(\bullet^2).

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V.

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			75 5000

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